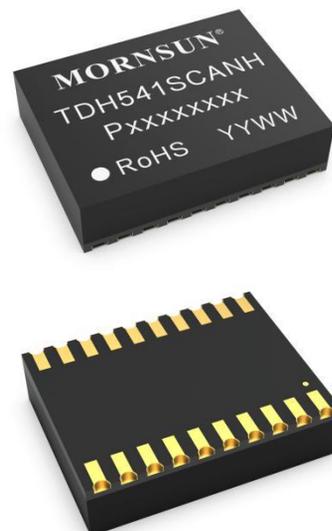


## TD(H)541SCANH DFN package isolated CAN transceiver

### Features

- Ultra-small, ultra-thin, chip scale DFN package
- Compliant with ISO11898-2 standard
- Integrate 5V efficiently power supply
- I/O power supply range supports 3.3V and 5V microprocessors
- High isolation to 3000VDC (TDH541SCANH 5000VDC)
- Bus-Pin ESD protection up to 15kV(HBM)
- Baud rate up to 1Mbps
- -40V to +40V bus fault protection
- >25kV/us CMTI
- TXD dominant time-out function
- Low communication delay
- The bus supports maximum 110 nodes
- Industrial operating ambient temperature range: -40°C to +125°C
- Meet AEC-Q100 standards
- EN62368 approval
- Moisture Sensitivity Level (MSL) 3

### Package



### Applications

- Industrial automation, control, sensors and drive systems
- Building and greenhouse environmental control(HVAC) automation
- Security system
- Transport
- Medical treatment
- Telecommunication
- CAN Bus standard such as CAN open, Device Net, NMEA2000, ARNIC825, ISO11783, CAN Kingdom, CAN aerospace

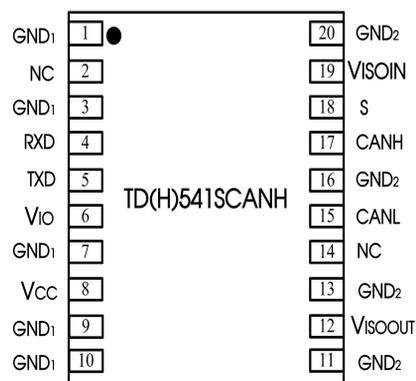
### Functional Description

TD(H)541SCANH is a isolated CAN Bus transceiver, which is compliant with ISO11898-2 standard. Their logic side supports 3.3V and 5V logic level conversion. TD(H)541SCANH integrate 5 V efficiently power. The TD(H)541SCANH provide differential transmitting and receiving capability between the CANH protocol controller and the physical layer bus. It is capable of running at data rates of up to 1 Mbps. The device has the function of series line, over-voltage(-40V to 40V), ground loss protection and thermal shutdown so that it is especially suitable for working in harsh environment.

## Contents

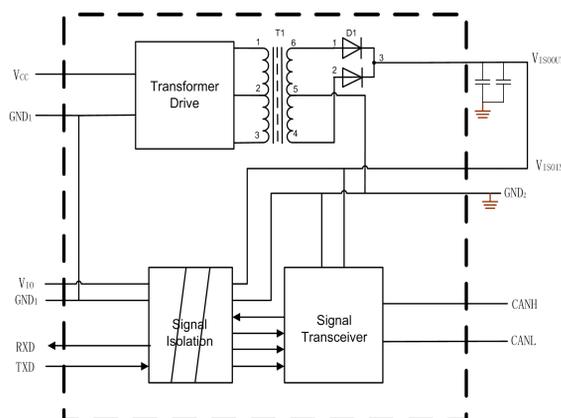
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### Pin Connection



Note: All GND<sub>1</sub> pins are internally connected;  
All GND<sub>2</sub> pins are internally connected.

### Internal Block Diagram



### Function Table

Letter	Description
H	High-Level
L	Low-Level
X	Unrelated
Z	High Impedance

Table 1. Driver Function table

INPUTS		OUTPUTS		Bus State
TXD	S	CANH	CANL	
L	L ( Or No Connection )	H	L	Dominant
H ( Or No Connection )	X	Z	Z	Recessive
X	H	Z	Z	Recessive

Table 2. Receiver Function table

V <sub>ID</sub> =CANH-CANL	RXD	Bus State
V <sub>ID</sub> ≥0.9V	L	Dominant
0.5 < V <sub>ID</sub> < 0.9V	Uncertainty	Uncertainty
V <sub>ID</sub> ≤0.5V	H	Recessive
OPEN	H	Recessive

## Pin Descriptions

Pin Number	Pin Name	Pin Functions
1	GND <sub>1</sub>	Ground(Logic side)
2	NC	No connect
3	GND <sub>1</sub>	Ground(Logic side)
4	RXD	Receiver output pin.
5	TXD	Driver input pin
6	V <sub>IO</sub>	Isolation power supply pin. By using 0.1uF ceramic capacitance ground1.
7	GND <sub>1</sub>	Ground(Logic side)
8	V <sub>CC</sub>	Power supply pin. By using 1uF ceramic capacitance ground1.
9	GND <sub>1</sub>	Ground(Logic side)
10	GND <sub>1</sub>	Ground(Logic side)
11	GND <sub>2</sub>	Ground (Bus side)
12	V <sub>ISOOUT</sub>	Insulation power output. By using 1uF ceramic capacitance ground2. The pin needs to be connected to pin19 in application.
13	GND <sub>2</sub>	Ground (Bus Side)
14	NC	No connect
15	CANL	Low level CAN voltage input/output
16	GND <sub>2</sub>	Ground (Bus side)
17	CANH	High level CAN voltage input/output
18	S	Ground Pin. In normal applied, this pin no connect or connect to ground2.
19	V <sub>ISOIN</sub>	Insulation power input. By using 0.1F ceramic capacitance ground2. The pin needs to be connected to pin12 in application.
20	GND <sub>2</sub>	Ground (Bus side)

## Absolute Maximum Ratings

General test conditions: Free-air, normal operating temperature range (unless otherwise specified).

PARAMETERS	UNIT
Supply voltage, V <sub>CC</sub>	-0.3V to +5.6V
Digital input voltage (TXD, RXD)	-0.3V to +6V
Bus voltage (CANH, CANL)	-40 to 40V
Receiver output current	-15 to 15mA
Operating temperature range	-40°C to +125°C
Storage temperature range	-50°C to +130°C
Reflow soldering temperature	Peak temp. ≤250°C, maximum duration ≤60s at 217°C. Please also refer to IPC/JEDEC J-STD-020D. 3.

Important: Exposure to absolute maximum rated conditions for an extended period may severely affect the device reliability, and stress levels exceeding the "Absolute Maximum Ratings" may result in permanent damage.

## Recommended Operating Conditions

PARAMETERS		Min.	Nom.	Max.	Unit
V <sub>CC</sub>	Power supply	4.75	5	5.25	V
V <sub>IO</sub>	Power supply(Logic Side)	2.75		5.25	V
V <sub>I</sub> or V <sub>IC</sub>	Voltage at any bus terminal (differential mode)	-40		40	V
V <sub>IH</sub>	High-level input voltage(TXD)	2			V
V <sub>IL</sub>	Low-level input voltage(TXD)			0.8	V
I <sub>OH</sub>	High-level output current	Driver	-70		mA
		Receiver V <sub>CC</sub> =5V	-4		
I <sub>OL</sub>	Low-level output current	Driver		70	mA
		Receiver V <sub>CC</sub> =5V		4	
T <sub>A</sub>	Operating temperature range	-40		125	°C

I <sub>CC</sub>	Recessive mode current		20	35	mA
I <sub>CC</sub>	Working current	V <sub>CC</sub> = 5V, R <sub>L</sub> = 60Ω ; TXD signal : f=500kHz ; Duty=50%	35	55	mA
	Signaling rate		40	1000	kbps

## Electrical Characteristics

General test conditions and V<sub>CC</sub>=V<sub>IO</sub>= 5V, Ta = 25°C (unless otherwise specified).

PARAMETERS		CONDITIONS	Min.	Nom.	Max.	Unit
<b>Driver</b>						
V <sub>O(D)</sub>	Dominant CANH output voltage	Figure 8 V <sub>TXD</sub> = 0 V, R <sub>L</sub> = 60 Ω	2.75	3.5	4.5	V
	Dominant CANL output voltage		0.5	1.5	2.25	
V <sub>O(R)</sub>	Recessive bus voltage	Figure 8 V <sub>TXD</sub> = 2 V, R <sub>L</sub> = 60 Ω	2	2.5	3	V
V <sub>OD(D)</sub>	Differential output voltage	Figure 8 V <sub>TXD</sub> = 0 V, t < t <sub>lo(dom)TXD</sub> , V <sub>CC</sub> =4.75 V to 5.25 V, R <sub>L</sub> = 50 to 65 Ω	1.5		3	V
V <sub>OD(R)</sub>	Recessive differential output voltage	Figure 8 V <sub>TXD</sub> = 5 V, R <sub>L</sub> = 60 Ω	-0.12		0.012	V
		V <sub>TXD</sub> = 5 V, No load	-0.5		0.05	
I <sub>IH</sub>	TXD High-level input current	V <sub>TXD</sub> = 2 V	2			mA
I <sub>IL</sub>	TXD Low-level input current	V <sub>TXD</sub> = 0.8 V	2			mA
R <sub>TXD</sub>	Internal TXD Pull up Resistor			9.1		kΩ
<b>Receiver</b>						
V <sub>IT+</sub>	Positive-going input threshold voltage	Figure 11		750	900	mV
V <sub>IT-</sub>	Negative-going input threshold voltage		500	650		mV
V <sub>hys</sub>	Hysteresis voltage (V <sub>IT+</sub> - V <sub>IT-</sub> )			120		mV
V <sub>OH</sub>	High-level output voltage	I <sub>OH</sub> = -4 mA, Figure 9	V <sub>IO</sub> - 0.4	V <sub>IO</sub> - 0.2		V
		I <sub>OH</sub> = -20 uA, Figure 9	V <sub>IO</sub> - 0.4	V <sub>IO</sub> - 0.2		
V <sub>OL</sub>	Low-level output voltage	I <sub>OL</sub> = 4 mA, Figure 9		0.2	0.4	V
		I <sub>OL</sub> = 20 uA, Figure 9		0	0.4	
C <sub>I</sub>	Input capacitance to ground (CANH or CANL)	V <sub>TXD</sub> = 5 V, V <sub>I</sub> = 0.4 sin(4E6 π t) + 2.5 V		13		pF
C <sub>ID</sub>	Differential input capacitance	V <sub>TXD</sub> = 5 V, V <sub>I</sub> = 0.4 sin(4E6 π t)		5		pF
R <sub>ID</sub>	Differential input resistance	V <sub>TXD</sub> = 5 V	15	30	40	kΩ
R <sub>IN</sub>	Input resistance (CANH or CANL)	V <sub>TXD</sub> = 5 V	30		80	kΩ
R <sub>I(m)</sub>	Input resistance matching: [1 - R <sub>IN(CANH)</sub> / R <sub>IN(CANL)</sub> ] × 100%	V <sub>CANH</sub> = V <sub>CANL</sub>	-3%	0%	3%	
ESD	HBM	CANH, CANL pin to GND			±15	kV
		Other pins			±2	kV
	Contact	CANH, CANL pin to GND			±2	kV
EFT	IEC61000-4-4 : Perf. Criteria B	CANH, CANL and GND			±2	kV
Surge	IEC61000-4-5 : Perf. Criteria B	CANH, CANL and GND(Common Mode)			±2	kV
	Isolation voltage	TD541SCANH			3000	VDC
		TDH541SCANH			5000	VDC
	Insulation resistance		1000			MΩ
	Isolation capacitor			3		pF
CMTI	Common Mode Transient Immunity	V <sub>TXD</sub> = V <sub>CC</sub> or 0 V, V <sub>CM</sub> = 1 kV, transient magnitude = 800 V	25			kV/us

## Transmission Characteristics

General test conditions and V<sub>CC</sub>=V<sub>IO</sub>= 5V, Ta = 25°C (unless otherwise specified).

PARAMETERS		CONDITIONS	Min.	Nom.	Max.	Unit
t <sub>onTXD</sub>	Propagation delay TXD On to bus active	R <sub>L</sub> = 60 Ω, C <sub>L</sub> = 100 pF, see Figure 10 and Figure 12		80	150	ns
t <sub>offTXD</sub>	Propagation delay TXD Off to bus inactive			80	200	ns
t <sub>onRXD</sub>	Propagation delay RXD On to			60	300	ns

PARAMETERS		CONDITIONS	Min.	Nom.	Max.	Unit
	receiver active					
$t_{offRXD}$	Propagation delay RXD Off to receiver inactive	$C_L=100\text{ pF}$		60	250	ns
$t_{TXD\_DTO}$	Dominant time-out time		1.2		3.8	ms

## Physical Specifications

PARAMETERS	Value	Unit
Weight	0.9(Typ.)	g

## Typical Performance Curves

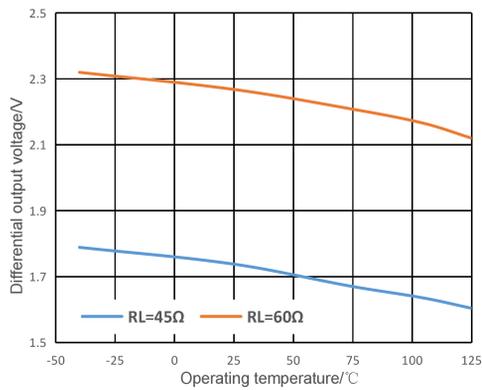


Figure 1. Drive differential output voltage dominant VS Temperature

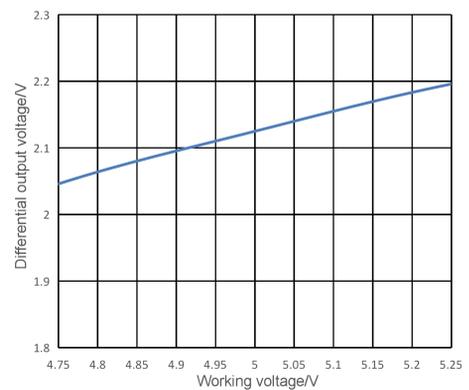


Figure 2. Drive differential output voltage dominant VS Working voltage

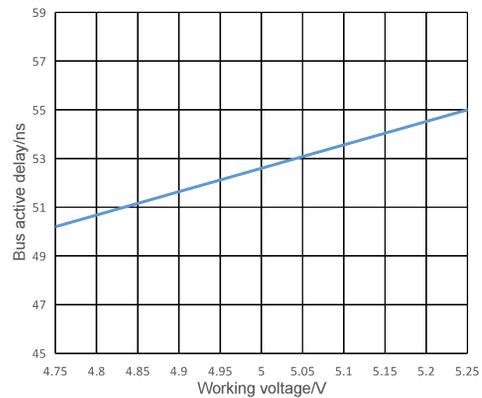


Figure 3. Propagation delay from TXD On to bus active VS Temperature

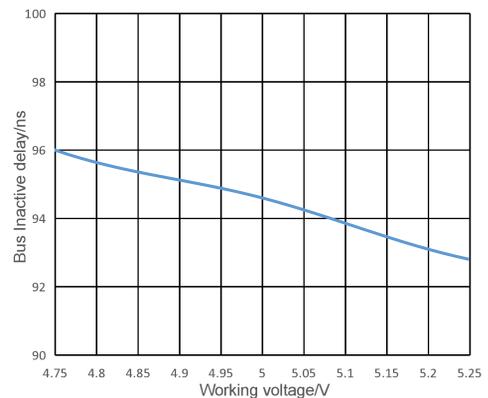


Figure 4. Propagation delay from TXD Off to bus inactive VS Temperature

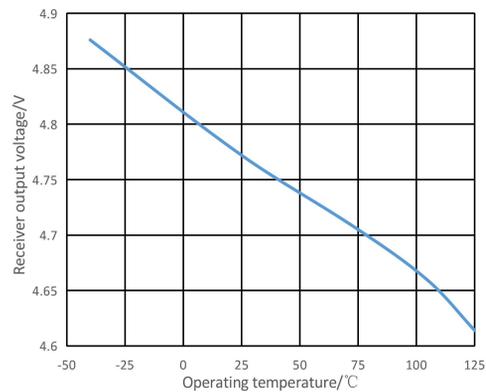


Figure 5. Receiver output voltage VS Temperature

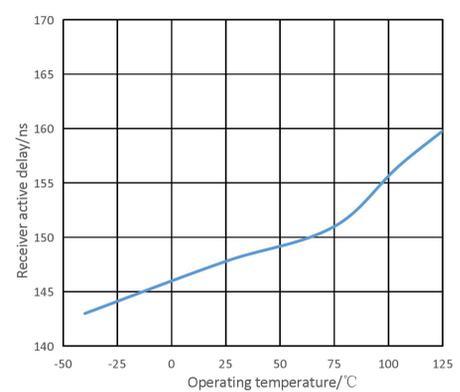


Figure 6. Receiver active delay VS Operating temperature

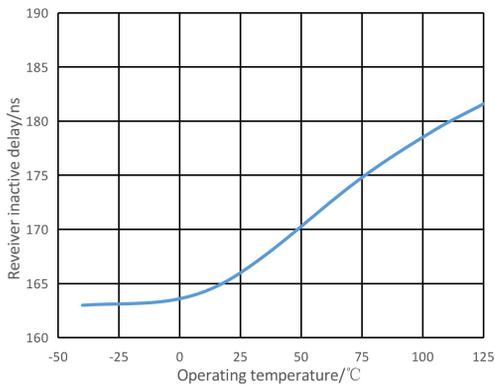


Figure 7. Receiver inactive delay VS Operating temperature

## Test Circuits

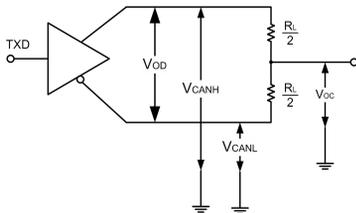


Figure 8. Driver test circuit

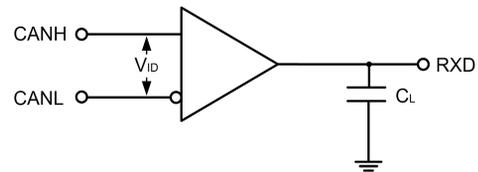


Figure 9. Receiver test circuit

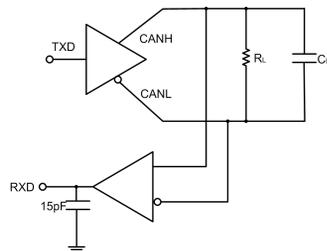


Figure 10. Switching characteristics test circuit

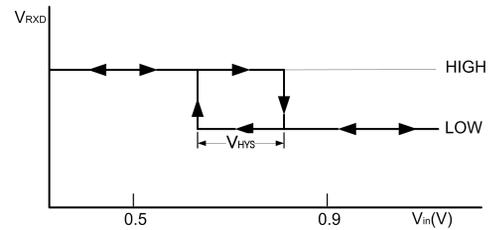


Figure 11. Receiver input hysteresis

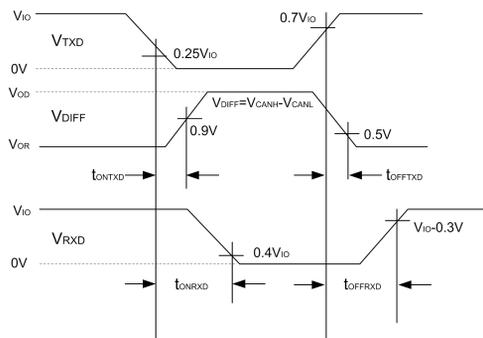


Figure 12. Drive and receiver propagation delay

## Detailed Description

TD(H)541SCANH is a CAN of a style of separation transceiver with the ability of differential signal transmission between the bus and CAN protocol controller, it the inner integration insulate DC/DC power supply. which is compliant with ISO11898-2 standard.

Short-circuit protection: TD(H)541SCANH has current-limiting protection to prevent the drive circuit from short-circuiting to positive and negative supply voltages. The power dissipation increases when a short circuit occurs. The short-circuit protection function protects the driver stage from damage.

Over-temperature protection: TD(H)541SCANH has over-temperature protection. When the junction temperature exceeds 160°C, the current in the driver stage will decrease. Because the drive tube is the primary energy consuming component, current reduction can reduce power consumption and reduce chip temperature. At the same time, the rest of the chip remains functional.

Dominant time-out function: TD(H)541SCANH has dominant time-out function to prevent if the pin TXD is forced to a permanent low level due to a hardware or software application failure, the built-in TXD dominant timeout timer circuit prevents the bus line from being driven to a permanent dominant state (blocking all network traffic). The timer is triggered by the negative edge on pin TXD.

If the low level on pin TXD lasts longer than the internal timer value ( $t_{TXD\_DTo}$ ), the transmitter will be disabled and the drive bus will enter a recessive state. The timer is reset by the positive edge on pin TXD.

## Application circuit

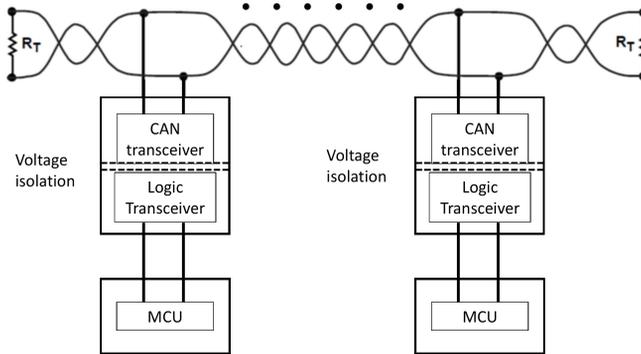


Figure 13. The typical model applies telephone

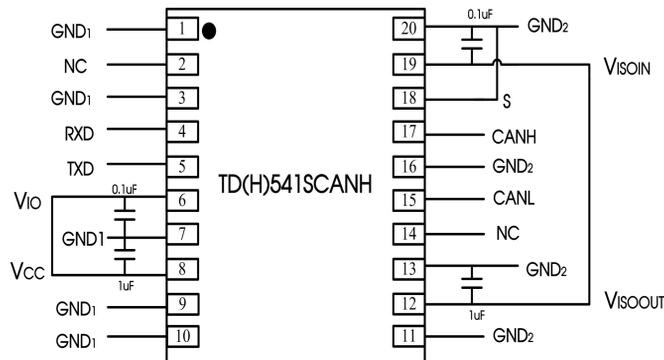


Figure 14. Type PCB layout

In General,  $V_{cc}$  and  $V_{io}$  can be shorted (Figure 14) if the controller doesn't support 5V signal input, it can power 3.3V for  $V_{io}$ . But it needs to power 5.5V for  $V_{cc}$ .

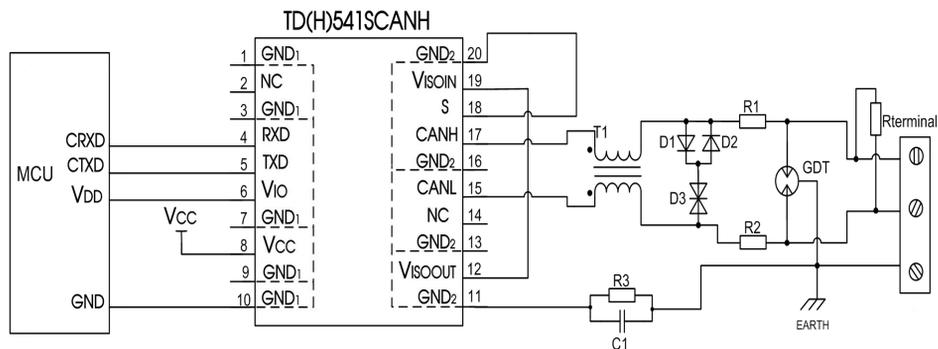


Figure 15. Port protection circuit for harsh environments

Recommended components and values:

Component	Recommended part, value	Component	Recommended part, value
R3	1M $\Omega$	D1、D2	1N4007
C1	1nF, 2kV	D3	SMBJ30CA
T1	ACM2520-301-2P	R <sub>terminal</sub>	120 $\Omega$
GDT	B3D090L	R1、R2	2.7 $\Omega$ /2W

When the module is used in applications with harsh environment, it can be susceptible to large energy like lightning strike, etc. in which case, it is essential to add an adequate protection circuit to the CAN signal ports to protect the system from failure and maintain a reliable bus communication. Figure 15 provides a recommended protection circuit design for high-energy lightning surges, with a degree of protection related to the selected

protection device. Parameter description lists a set of recommended circuit parameters, which can be adjusted according to the actual application situation. Also, when using the shielded cable, the reliable single-point grounding of the shield must be achieved.

Note: The recommended components and values is a general guideline only and must be verified for the actual user's application. We recommended using PTC's for R1 and R2 and to use fast recovery diodes for D1 and D2.

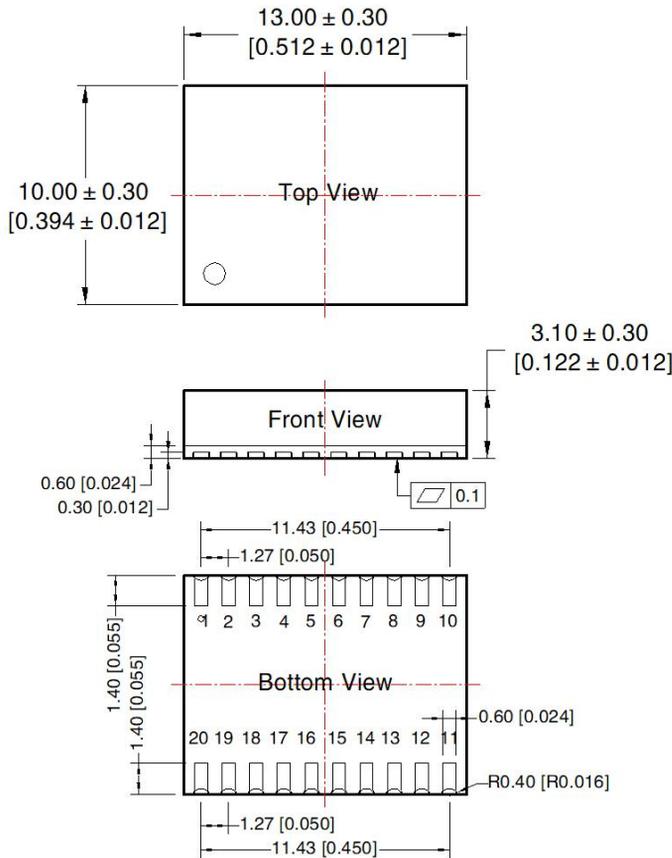
## Using Suggests

- ① Power isolation  $V_{ISOOUT}$  need through a series of capacitors connected to the output pin  $V_{ISOIN}$ , the power supply is not recommended for other purposes, otherwise it may cause the bus voltage did not meet the requirements of communication, causes the communication failure.
- ② Hot-swap is not supported.
- ③ If the external input of TXD is insufficient, the pull-up resistor should be added according to the situation.
- ④ Refer to *IPC 7093* for the welding process design of this product. For detailed operation guidance, please refer to *Hot Air Gun Welding Operation Instruction for DFN Package Product* or *Welding Operation Instruction for DFN Package Product*.

## Ordering Information

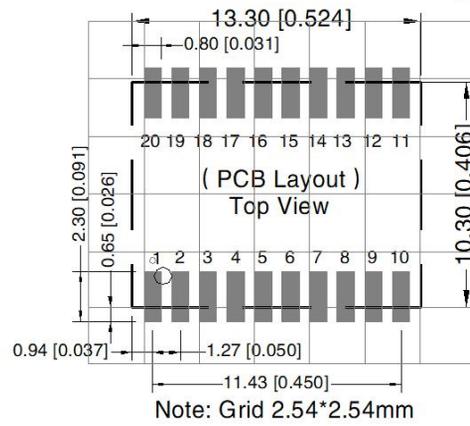
Part number	Package	Number of pins	Product marking	Tape & Reel
TD541SCANH	DFN	20	TD541SCANH	300/REEL
TDH541SCANH	DFN	20	TDH541SCANH	300/REEL

## Package Information

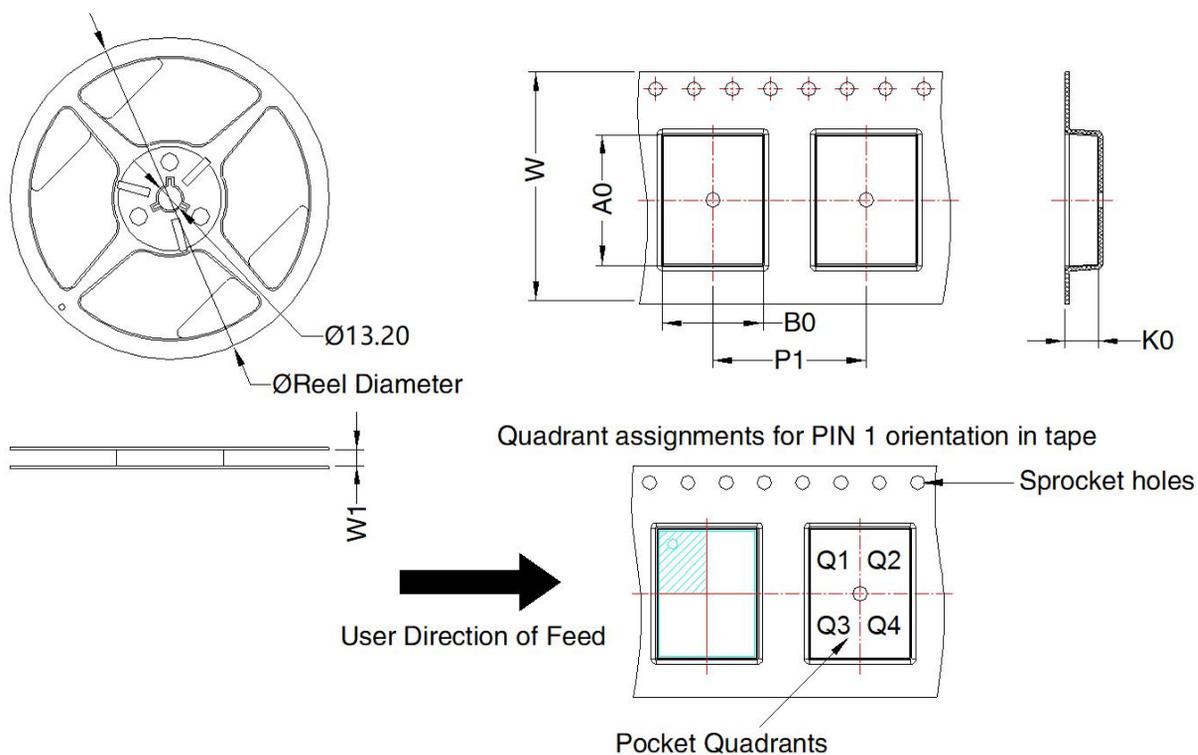


Note:  
Unit: mm[inch]  
Pin diameter tolerances:  $\pm 0.10$  [± 0.004]

## THIRD ANGLE PROJECTION



Pin-Out			
Pin	Mark	Pin	Mark
1	GND <sub>1</sub>	11	GND <sub>2</sub>
2	NC	12	$V_{ISOOUT}$
3	GND <sub>1</sub>	13	GND <sub>2</sub>
4	RXD	14	NC
5	TXD	15	CANL
6	$V_{IO}$	16	GND <sub>2</sub>
7	GND <sub>1</sub>	17	CANH
8	$V_{CC}$	18	S
9	GND <sub>1</sub>	19	$V_{ISOIN}$
10	GND <sub>1</sub>	20	GND <sub>2</sub>



Device	Package Type	Pin	MPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TD(H)541SCANH	DFN 10x13	20	300	180.0	24.4	13.52	10.52	3.5	16.0	24.0	Q1

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